# LeverReversals

# **A Whisker client**

by Rudolf Cardinal

www.whiskercontrol.com

Copyright (C) Cambridge University Technical Services Ltd.

Distributed by Campden Instruments Ltd (www.campden-inst.com)



# LeverReversals

### © Cambridge University Technical Services Ltd

All rights reserved. No parts of this work may be reproduced in any form or by any means - graphic, electronic, or mechanical, including photocopying, recording, taping, or information storage and retrieval systems - without the written permission of the publisher.

Products that are referred to in this document may be either trademarks and/or registered trademarks of the respective owners. The publisher and the author make no claim to these trademarks.

While every precaution has been taken in the preparation of this document, the publisher and the author assume no responsibility for errors or omissions, or for damages resulting from the use of information contained in this document or from the use of programs and source code that may accompany it. In no event shall the publisher and the author be liable for any loss of profit or any other commercial damage caused or alleged to have been caused directly or indirectly by this document.

Printed: March 2024 in Cambridge, UK

# Creator (Whisker)

Rudolf N. Cardinal

Design and Programming (Whisker) Rudolf N. Cardinal Michael R. F. Aitken

## Legal Advisor (CUTS)

Adjoa D. Tamakloe

## Sales (Campden)

Julie Gill

### Contacting the authors:

For information about Whisker, visit http://www.whiskercontrol.com/.

If you have sales enquiries about Whisker, contact Campden Instruments Ltd at http://www.campden-inst.com/.

If you have comments or technical enquiries that cannot be answered by the sales team, contact the authors:

Rudolf Cardinal (rudolf@pobox.com) Mike Aitken (m.aitken@psychol.cam.ac.uk)

# **Table of Contents**

	Foreword	1
Part I	LeverReversals	2
1	About LeverReversals	. 2
2	Required devices	. 2
3	Using the task	. 3
4	Parameters	. 4
	Index	7

# Foreword

#### WARNING

Whisker is a system designed for research purposes only, and should never be used to control medical apparatus or other devices that could endanger human life.

#### DISCLAIMER

The authors, copyright holders, and distributors disclaim all responsibility for any adverse effects that may occur as a result of a user disregarding the above warning.

# 1 LeverReversals

# 1.1 About LeverReversals

## Purpose

Autoshaping using levers as the CS.

### Software requirements

Requires Whisker v2.0 or greater.

### Data storage

- Text-based output to disk.
- ODBC data storage to a database (supplied).

### Author

Rudolf Cardinal (rudolf@pobox.com).

### Copyright

Copyright © Cambridge University Technical Services Ltd

### Version history

- v0.1 (10-13 Feb 2005). Written.
- v0.2 (21 Feb 2005). Dialogue box resized. Facility to begin trials on a centralizing nosepoke. Symmetric reward/punishment with multiple responses. Latency to last correct/incorrect response explicitly recorded. "X correct in last Y" reversal criterion fixed so it only counts back trials within the current reversal.
- v1.0 (8 March 2007). Easier compilation for users.
- v2.0 (12 Jan 2009). Server default changed from "loopback" to "localhost" (Windows Vista compatibility and more general standardization).

# 1.2 Required devices

The program requires to claim devices in groups named **box0**, **box1**, **box2**... with device names as listed below in bold:

// Names of lines the program expects to be able to claim NOSEPOKE // input LEFTLEVER // input RIGHTLEVER // input HOUSELIGHT // output TRAYLIGHT // output PUMP // output DIPPER // output LEFTLEVERCONTROL // output RIGHTLEVERCONTROL // output LEFTLIGHT // output RIGHTLIGHT // output PELLET // output

 $\ensuremath{\prime\prime}\xspace$  )/ Aliases used while the program is in full flight, which it therefore expects

3

 $\ensuremath{\operatorname{not}}$  to be present on the server:

Please ensure that these devices are available and listed in the device definition file in use by the server.

# 1.3 Using the task

When you run the task, the main screen looks as follows:

🚚 LeverReversals	_ 🗆 🗵	
1. Connect to a Whisker server named loopba	on port 3233	<u>C</u> onnect
2. Claim box number 0		Claim
3. Choose (or view) the task parameters		<u>P</u> arameters
4. Start the task	Ť	<u>S</u> tart
State of the box:		
Status messagesClear		
	Triak	
	Correct trials: Incorrect trials Reinforcements:	
	About	<u>H</u> elp

You must connect to a Whisker server, claim an operant chamber (box), and set up the <u>parameters</u> for your task. Once that's done, the traffic lights will turn amber. When you are ready, press *Start* to begin the task.

When the task finishes, it saves data to disk and pops up a new dialogue box for you to select a database to store the data to. (The data sources are configured under *Control Panel*  $\rightarrow$  *ODBC*.) If you previously specified an ODBC data source in the parameters, that data source is used automatically and you will only see a dialogue box if something goes wrong and the program needs your input.

ile Data Source Machine Dat						
Data Source Name	Туре	Description 🔶				
ConditionedReinforcement	User	ConditionedReinforcement (prototype)				
dBASE Files	User					
DeluxeCD	User	_				
Excel Files	User					
FiveChoice_prototype	User	FiveChoice_prototype				
FoxPro Files	User					
ImpulsiveChoice_prototype	User	ImpulsiveChoice_prototype				
LeverReversals_prototype	User	LeverReversals_prototype				
MonkeyCantab	User	MonkevCantab (sample)				
<u> • </u>		<u> </u>				
		No.				
		<u>N</u> ew				
A Machine Data Source is specific to this machine, and cannot be shared.						
		er on this machine. "System" data				
		machine, or by a system-wide service.				
1						
		OK Cancel Help				

# 1.4 Parameters

The basic task runs as follows:

- Overall structure: trials are separated by intertrial intervals (ITIs).
- In the ITI, the operant chamber is in darkness.
- If the rat is to be required to nosepoke to initiate the trial, then the houselight (and perhaps traylight) will come on in the "pre-trial" state, until the rat nosepokes. A time limit can be set on this stage.
- At the start of the trial itself, the houselight comes on (if it isn't on already) and two levers are extended. A light may also appear (and perhaps flash) above one or other of the levers.
- The rat has to select the correct lever. This is either determined spatially ("the left lever is always correct" or "the right lever is always correct") or with reference to the light ("the lever on the same side of the light is always correct" or "the lever on the opposite side as the light is always correct"). The rat must discover this.
- Once the rat has made a certain (user-specifiable) number of responses on the correct lever, it
  is rewarded (and the houselight will stay on for a while, and the traylight in the food alcove may
  also come on). Optionally, if it makes a response on the incorrect lever, or takes too long, it
  loses and the trial finishes.
- To make things harder, the rat can be reinforced probabilistically (i.e. the probability of reward given that it does the right thing, or of reward given that it does the wrong thing) can also be set manually.
- Overall trial number limits or session time limits can be set.
- There is an option to select the correct response location pseudorandomly (so that there's a guarantee of equal number of left/right trials (in the case of the "same or opposite side as the light" task), or so the irrelevant distractor light (for the "spatial plus distractor light" task) appears equally left/right. This is done by drawing left/right locations "without replacement" from a list of a user-specified size. If the user specifies a value ("multiplier") of 1, then the list starts off by containing the values {Left, Right}. One is picked at random, without replacement, for each trial so in every two trials, there's be one Left trial and one Right trial. If the multiplier was 3, then in every 6 trials there'd be guaranteed to be 3 Left and 3 Right trials, and so on. The

larger the multiplier, the closer this pseudorandom behaviour is to genuinely random selection (in which there's no way for the subject to predict what's coming next, but there's always the possibility of very long sequences of, for example, Left trials).

• This is a **reversal** task... so the experimenter can reverse subjects by hand (between sessions) by choosing whether the Left or Right response (in the case of the spatial task) or the Same or Opposite response (in the case of the light-tracking task) is correct at the start of each session. But there's also an option for **within-session reversal**, in which case the reversal can occur automatically when X trials within at most the last Y trials have been performed correctly by the subject.

The parameters dialogue box looks like this:

Set parameters for LeverReversals							
Subject details							
Load config Rat ID: xxx Session number: 1							
Save config Comment: (add your comment here)							
Data recording							
S <u>e</u> t file							
ODBC data source name (see Control Panel). Blank to choose later:							
Reinforcer							
Pump - Infusion duration (s): 7.28							
O Dipper # dips: 1 Dip time (s): 5 Inter-dip time (s): 1 ☑ Down at rest							
Pellets - # pellets: 1 Pulse length (ms): 45 Time between pellets (s): 0.5							
Reversal learning task settings							
<ul> <li>Spatial ("Left [or right] is correct")</li> <li>Begin with L correct (if unticked, R will be correct)</li> <li>Lights are on anyway, on random sides, as a distractor</li> </ul>							
C Light-tracking ("Same side as light [or opposite]")							
Subject must nosepoke to begin the trial (centring itself in the process) Time limit in seconds (0 = none): 10							
■ Flash the lights, when they're being used On time (s): 0.5 Off time (s): 0.5							
Choose correct response or distractor location (L/R) pseudorandomly, rather than randomly							
Draw without replacement from a list of length 2 x 1 = 2							
Require 1 responses on the correct lever before success is scored, or on the incorrect lever before failure is scored							
✓ Require consecutive responses (i.e. no responding allowed on the incorrect lever at all)							
<ul> <li>✓ p(reward   correct) = 1; p(reward   incorrect) = 0</li> <li>✓ Use traylight when reward delivered or rat must nosepoke</li> </ul>							
When reward has finished being delivered, houselight (+/- traylight) stays on for 5							
seconds or until food is collected (nosepoke in alcove).							
If a trial has not been completed within 20s, terminate it as an omission (0 means no time limit).							
Time between trials (s): from 5 to 15							
Reverse within a session when 27 of at most the last 30 trials in the current reversal performed correctly							
Max. no. of trials (0 = no limit): 60 Session time limit (min) (0 = no limit): 30 Lever debounce time (ms): 10							

To pick an ODBC database **in advance** of finishing, click *Pick* and you will be offered the ODBC Data Source picker (below). Your choice will be recorded and will apply to this subject from now on (or until you specify a different source).

6

Data Source Name	Туре	Description				
ConditionedReinforcement	User	ConditionedReinforcement (prototype)				
dBASE Files	User					
DeluxeCD	User	_				
Excel Files	User					
FiveChoice_prototype	User	FiveChoice_prototype				
FoxPro Files	User					
ImpulsiveChoice_prototype	User	ImpulsiveChoice_prototype				
LeverReversals_prototype	User	LeverReversals_prototype				
MonkeyCantab	User	MonkevCantab (sample)				
		·				
		New				
		<u><u>n</u>ew</u>				
A Machine Data Source is en	acific to th	is machine, and espinet he shared				
		is machine, and cannot be shared.				
"User" data sources are specific to a user on this machine. "System" data sources can be used by all users on this machine, or by a system-wide service.						
sources can be ased by an as	sers off ans	indefinite, of by a system made service.				

If you don't specify an ODBC data source now, or you delete the value in the "ODBC data source name" box, you'll be asked to choose when the task ends (and that choice will only apply to the session in progress).

Index	7

# Index

# - L -

LeverReversals about 2 parameters 4 required devices 2 using 3